

# Convergence and Efficiency of Adaptive Importance Sampling techniques with partial biasing

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Joint work with

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Talk based on the paper

G. Fort, B. Jourdain, T. Lelièvre, G. Stoltz *Convergence and Efficiency of Adaptive Importance Sampling techniques with partial biasing*, arXiv:1610.0919

## Goal:

Explore the support of a distribution  $\pi d\lambda$  on  $X \subseteq \mathbb{R}^p$   
and/or compute integrals w.r.t.  $\pi$

$$\int_X f(x) \pi(x) d\lambda(x)$$

when  $\pi$  is highly metastable,  $p$  is large.

## Solution: based on Importance Sampling (IS)

Sample  $X_1, \dots, X_n, \dots \stackrel{i.i.d.}{\sim} \tilde{\pi} d\lambda$

Define the IS approximation

$$\int_X f \pi d\lambda \approx \frac{1}{n} \sum_{k=1}^n \underbrace{\frac{\pi(X_k)}{\tilde{\pi}(X_k)}}_{\text{importance ratio}} f(X_k).$$

## Motivation (2/4) - How to choose $\tilde{\pi}$ ?

- Define a partition of the support  $X$  (Molecular dynamics: Chipot, Pohorille (2007) and Lelievre, Rousset, Stoltz (2010); Statistics: Chopin, Lelievre, Stoltz (2012))

$$X = \bigcup_{i=1}^d X_i \quad d \text{ strata}$$

- A family of auxiliary distribution based on a local biasing  
For all *positive vector*  $\tau = (\tau(1), \dots, \tau(d))$   $\tau(i) > 0, \forall i$

$$\pi_{\tau}(x) \stackrel{\text{def}}{=} \frac{1}{\sum_{i=1}^d \frac{\theta_{\star}(i)}{\tau(i)}} \sum_{i=1}^d \frac{\pi(x)}{\tau(i)} \mathbb{I}_{X_i}(x),$$

where

$$\theta_{\star}(i) \stackrel{\text{def}}{=} \int_{X_i} \pi d\lambda, \quad \text{up to a constant, } \log \theta_{\star}(i) \text{ is the free-energy}$$

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Key property:  $\pi_{\theta_{\star}}(X_i) = 1/d$  – all the strata have the same weight: efficient to tackle multimodality ! but  $\theta_{\star}$  is unknown.

## Motivation - Adaptive Importance Sampling (3/4)

An *iterative* algorithm which

- Will learn on the fly the weight vector  $\theta_*$  through a **Stochastic Approximation** algorithm

$$\theta_{n+1} = \theta_n + \gamma_{n+1} H(\theta_n, X_{n+1})$$

where  $H$  is chosen so that  $\theta_*$  is the unique solution of

$$\int H(\theta, x) \pi_\theta(x) d\lambda(x) = 0.$$

- from draws  $X_{n+1}$

$$X_{n+1} \sim P_{\theta_n}(X_n, \cdot) \quad \text{kernel with inv. dist. } \pi_{\theta_n}$$

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$$X_{n+1} \sim P_{\theta_n}(X_n, \cdot) \quad \text{kernel with inv. dist. } \pi_{\theta_n}$$

If **convergence** is established

- An estimator of the free energy:  $\lim_n \theta_n = \theta_*$ .
- An approximation of the target distribution  $\pi$  - computed on the fly/online

$$\int f \pi d\lambda = \lim_n \frac{d}{n} \sum_{k=1}^n f(X_k) \left( \sum_{i=1}^d \theta_k(i) \mathbb{I}_{X_i}(X_k) \right)$$

## Motivation - Choice of the field $H(\theta, x)$ (4/4)

A family of algorithms: Wang Landau, Self Healing Umbrella Sampling (SHUS), Well-Tempered Metadynamics, SHUS $^g_\rho$

on the form

- 1 Given a new draw  $X_{n+1} \sim P_{\theta_n}(X_n, \cdot)$  with inv. dist.  $\pi_{\theta_n}$
- 2 Update a counter of the visits to a stratum

$$C_{n+1}(i) = C_n(i) + (\dots)^2 \mathbb{I}_{X_i}(X_{n+1}) \quad i = 1, \dots, d$$

- 3 Normalize the counter to obtain a weight vector

$$\theta_{n+1}(i) = \frac{C_{n+1}(i)}{\sum_{j=1}^d C_{n+1}(j)} = \theta_n(i) + \gamma_{n+1} \dots + O(\gamma_{n+1}^2) \quad i = 1, \dots, d$$

Fundamental: if  $X_{n+1} \in X_i$

$$\begin{aligned} C_{n+1}(i) &> C_n(i), & C_{n+1}(j) &= C_n(j), j \neq i \\ \implies \pi_{\theta_{n+1}}(X_i) &< \pi_{\theta_n}(X_i), & \pi_{\theta_{n+1}}(X_j) &= \pi_{\theta_n}(X_j). \end{aligned}$$

# **A Wang-Landau (WL) based algorithm**



# a WL based algorithm - algorithm (1/3)

(adapted from) the Wang-Landau algorithm (Wang and Landau, 2001)

*Input:*

- *initial values: a point  $X_0 \in X$  and a counter  $C_0 \in (\mathbb{R}_+^*)^d$*
- *a positive (deterministic) stepsize sequence  $\{\gamma_n, n \geq 0\}$*

*For  $n = 0, 1, \dots$*

- *Normalize the counter*

$$\theta_n(i) = \frac{C_n(i)}{\sum_{j=1}^d C_n(j)}, \quad \forall i = 1, \dots, d$$

- *Draw a new point:  $X_{n+1} \sim P_{\theta_n}(X_n, \cdot)$  kernel with inv. dist.  $\pi_{\theta_n}$*
- *Update the counter of the visited stratum*

$$C_{n+1}(i) = C_n(i) + \gamma_{n+1} C_n(i) \mathbb{I}_{X_i}(X_{n+1}), \quad \forall i = 1, \dots, d$$

## a WL based algorithm - convergence results (2/3)

On the form

$$\theta_{n+1}(i) = \theta_n(i) + \gamma_{n+1} \left( \theta_n(i) \mathbb{I}_{X_i}(X_{n+1}) - \sum_{j=1}^d \theta_n(j) \mathbb{I}_{X_j}(X_{n+1}) \right) + \gamma_{n+1}^2 O_{w.p.1.}(1).$$

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On the form

$$\theta_{n+1}(i) = \theta_n(i) + \gamma_{n+1} \left( \theta_n(i) \mathbb{I}_{X_i}(X_{n+1}) - \sum_{j=1}^d \theta_n(j) \mathbb{I}_{X_j}(X_{n+1}) \right) + \gamma_{n+1}^2 O_{w.p.1.}(1).$$

Under conditions on

- the strata and the target:  $0 < \inf_X \pi \leq \sup_X \pi < \infty$ ,  $\theta_*(i) > 0$ .
- the ergodicity of the kernels  $P_\theta$
- the stepsize sequence  $\gamma_n$ :  $\sum_n \gamma_n = +\infty$ ,  $\sum_n \gamma_n^2 < \infty$

it is proved asymptotic results (F., Jourdain, Kuhn, Lelièvre, Stoltz, 2015a)

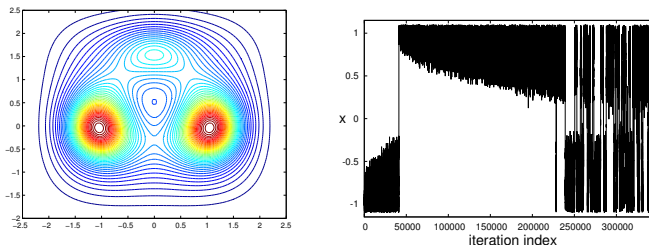
- 1 The a.s. convergence of the sequence  $\theta_n$  to  $\theta_*$ .
- 2 The "convergence" of the samples  $\{X_1, \dots, X_n, \dots\}$

$$\int f \pi d\lambda = \lim_n \frac{d}{n} \sum_{k=1}^n f(X_k) \left( \sum_{i=1}^d \theta_k(i) \mathbb{I}_{X_i}(X_k) \right) \quad a.s.$$

↪ very bad Effective Sample Size

# a WL based algorithm - convergence results (3/3)

and role of the stepsize sequence (F., Jourdain, Kuhn, Lelièvre, Stoltz, 2015b) in the transient phase



**Figure:** Left: level curves of the target density. Right: typical trajectory for  $\beta = 15$  when  $\gamma_n = \gamma_*/n^{0.6}$  with  $\alpha = 0.6$  and  $\gamma_* = 1$ .

- The density depends on a parameter  $\beta$ : large values of  $\beta$  increases the metastability phenomenon.
- We choose  $\gamma_n = \gamma_*/n^\alpha$   $\alpha \in (1/2, 1]$

$$\ln T_{(\alpha < 1)} = C(\alpha, \gamma_*) + \frac{1}{1 - \alpha} \ln \beta$$

$$\ln T_{(\alpha = 1)} = C(\gamma_*) + \frac{\mu_0}{1 + \gamma_*} \beta$$

↪ "self tuned" step size  $\gamma_n$

## **An Adaptive Importance Sampling with**

- self-tuned stepsize sequence**
- partial biasing to improve the IS step**

**SHUS <sub>$\rho$</sub> <sup>g</sup>**

## Self-tuned and Partially biasing algorithm (F., Jourdain, Lelièvre, Stoltz (2016))

*Input:*

- *initial values: a point  $X_0 \in X$  and a counter  $C_0 \in (\mathbb{R}_+^*)^d$*
- *a biasing function  $\rho$  and a stepsize control function  $g$*

*For  $n = 0, 1, \dots$*

- *Normalize the counter*

$$\theta_n(i) = \frac{C_n(i)}{\sum_{j=1}^d C_n(j)}, \quad \forall i = 1, \dots, d$$

- *Draw a new point:  $X_{n+1} \sim P_{\rho(\theta_n)}(X_n, \cdot)$  kernel with inv. dist.  $\pi_{\rho(\theta_n)}$*
- *Update the counter of the visited stratum  $\forall i = 1, \dots, d$*

$$C_{n+1}(i) = C_n(i) + \frac{\gamma}{g\left(\sum_{j=1}^d C_n(j)\right)} \left( \sum_{j=1}^d C_n(j) \right) \rho(\theta_n(i)) \mathbb{1}_{X_i}(X_{n+1}),$$

## The intuition for this new update rule of $C_n$

The samples  $X_n \stackrel{i.i.d.}{\sim} \pi$ ;

- ▶ A counter of the visits to each stratum

$$\begin{aligned} C_n(i) &= C_{n-1}(i) + \gamma \mathbb{1}_{X_i}(X_n) = C_0(i) + \gamma \sum_{k=1}^n \mathbb{1}_{X_i}(X_k) \Rightarrow C_n(i) \sim \gamma n \theta_*(i) \\ &= C_{n-1}(i) + \underbrace{\frac{\gamma}{\sum_{j=1}^d C_{n-1}(j)}}_{\gamma_n = O(1/n)} \left( \sum_{j=1}^d C_{n-1}(j) \right) \mathbb{1}_{X_i}(X_n) \end{aligned}$$

- ▶ The estimate of  $\theta_*$

$$\theta_n(i) = \theta_{n-1}(i) + \gamma_n \left( \mathbb{1}_{X_i}(X_n) - \sum_{j=1}^d \mathbb{1}_{X_j}(X_n) \right) + O(\gamma_n^2)$$

- ▶ For approximation of integrals

$$\int f \pi d\lambda \approx \frac{1}{n} \sum_{k=1}^n f(X_k)$$

## The intuition for this new update rule of $C_n$

The samples  $X_n \stackrel{i.i.d.}{\sim} \pi$ ;  $X_n \stackrel{i.i.d.}{\sim} \pi_{\rho(\theta_*)} \propto \sum_{i=1}^d \frac{\pi}{\rho(\theta_*(i))} \mathbb{I}_{X_i}$ ;

► A counter of the visits to each stratum

$$C_n(i) = C_{n-1}(i) + \underbrace{\frac{\gamma}{\sum_{j=1}^d C_{n-1}(j)}}_{\gamma_n = O(1/n)} \left( \sum_{j=1}^d C_{n-1}(j) \right) \rho(\theta_*(i)) \mathbb{I}_{X_i}(X_n)$$

► The estimate of  $\theta_*$

$$\theta_n(i) = \theta_{n-1}(i) + \gamma_n \left( \rho(\theta_*(i)) \mathbb{I}_{X_i}(X_n) - \sum_{j=1}^d \rho(\theta_*(j)) \mathbb{I}_{X_j}(X_n) \right) + O_{w.p.1}(\gamma_n^2)$$

► For approximation of integrals

$$\int f \pi d\lambda \approx \frac{1}{n} \sum_{k=1}^n f(X_k) \left( \sum_{j=1}^d \rho(\theta_*(j)) \mathbb{I}_{X_j}(X_k) \right) \left( \sum_{j=1}^d \frac{\theta_*(j)}{\rho(\theta_*(j))} \right)$$

The discrepancy between the weights is modified through  $\rho$ . ex.  $t^a, 0 < a < 1$



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► A counter of the visits to each stratum

$$C_n(i) = C_{n-1}(i) + \underbrace{\frac{\gamma}{g\left(\sum_{j=1}^d C_{n-1}(j)\right)}}_{\gamma_n \rightarrow 0} \left( \sum_{j=1}^d C_{n-1}(j) \right) \rho(\theta_*(i)) \mathbb{I}_{X_i}(X_n)$$

► The estimate of  $\theta_*$

$$\theta_n(i) = \theta_{n-1}(i) + \gamma_n \left( \rho(\theta_*(i)) \mathbb{I}_{X_i}(X_n) - \sum_{j=1}^d \rho(\theta_*(j)) \mathbb{I}_{X_j}(X_n) \right) + O_{w.p.1}(\gamma_n^2)$$

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The discrepancy between the weights is modified through  $\rho$ . ex.  $t^a, 0 < a < 1$

Control the step size through a function  $g$

## The intuition for this new update rule of $C_n$

The samples  $X_n \stackrel{i.i.d.}{\sim} \pi$ ;  $X_n \stackrel{i.i.d.}{\sim} \pi_{\rho(\theta_*)} \propto \sum_{i=1}^d \frac{\pi}{\rho(\theta_*(i))} \mathbb{I}_{X_i}$ ; The weight  $\theta_*$  is learnt along iterations

► A counter of the visits to each stratum

$$C_n(i) = C_{n-1}(i) + \frac{\gamma}{\underbrace{g\left(\sum_{j=1}^d C_{n-1}(j)\right)}_{\gamma_n \rightarrow 0}} \left( \sum_{j=1}^d C_{n-1}(j) \right) \rho(\theta_{n-1}(i)) \mathbb{I}_{X_i}(X_n)$$

► The estimate of  $\theta_*$

$$\theta_n(i) = \theta_{n-1}(i) + \gamma_n \left( \rho(\theta_{n-1}(i)) \mathbb{I}_{X_i}(X_n) - \sum_{j=1}^d \rho(\theta_{n-1}(j)) \mathbb{I}_{X_j}(X_n) \right) + O_{w.p.1}(\gamma_n^2)$$

► For approximation of integrals

$$\int f \pi d\lambda \approx \frac{1}{n} \sum_{k=1}^n f(X_k) \left( \sum_{j=1}^d \rho(\theta_{k-1}(j)) \mathbb{I}_{X_j}(X_k) \right) \left( \sum_{j=1}^d \frac{\theta_{k-1}(j)}{\rho(\theta_{k-1}(j))} \right)$$

The discrepancy between the weights is modified through  $\rho$ . ex.  $t^a, 0 < a < 1$

Control the step size through a function  $g$

- 1 On the target density  $0 < \inf_X \pi \leq \sup_X \pi < \infty$  and  $\theta_*(i) > 0$
- 2 On the ergodic behavior of the kernels Hastings-Metropolis kernel, with proposal  $q(x, y)d\lambda(y)$  such that  $\inf_{X^2} q > 0$
- 3 On the function  $\rho \rightarrow$  satisfied with  $\rho(t) = t^a$  with  $a \in [0, 1)$
- 4 On the function  $g$ , chosen of the form  $g(s) = (\ln(1 + s))^{\alpha/(1-\alpha)}$  with  $\alpha \in (1/2, 1)$

## Convergence results (1/2)

By using sufficient conditions for convergence of Adaptive MCMC samplers  $\mathbb{F}_\cdot$ ,  
Moulines, Priouret (2012) and convergence of Stochastic Approximation algo with controlled  
Markovian dynamics Andrieu, Moulines, Priouret (2005)

► On the random sequence  $\gamma_n$  almost-surely,

$$\lim_n \gamma_n n^\alpha = (1 - \alpha)^\alpha \gamma^{1-\alpha} \left( \sum_{j=1}^d \frac{\theta_\star(j)}{\rho(\theta_\star(j))} \right) \quad \text{a.s.}$$

► On the weight sequence  $\theta_n$  almost-surely,

$$\lim_n \theta_n = \theta_\star$$

► On the Importance Sampling step almost-surely,

$$\lim_n \frac{1}{n} \sum_{k=1}^n f(X_k) \left( \sum_{j=1}^d \rho(\theta_{k-1}(j)) \mathbb{I}_{X_j}(X_k) \right) \left( \sum_{j=1}^d \frac{\theta_{k-1}(j)}{\rho(\theta_{k-1}(j))} \right) = \int f \pi d\lambda$$

We wrote the results in the case

$$\rho(t) = t^a \text{ with } a \in [0, 1)$$

$$g(s) = (\ln(1 + s))^{\alpha/(1-\alpha)} \text{ with } \alpha \in (1/2, 1)$$

but our convergence analysis also includes the case

- $\rho(t) = t$  and  $g(s) = s$  (F., Jourdain, Lelièvre, Stoltz, 2016)

In that case, our algorithm is the **Self Healing Umbrella Sampling** algorithm

(Marsili et al. 2006)

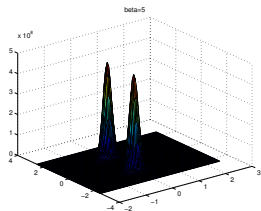
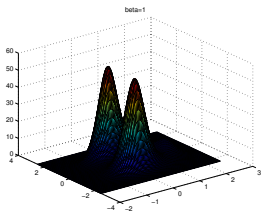
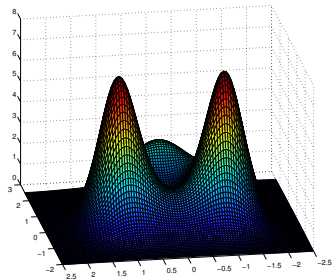
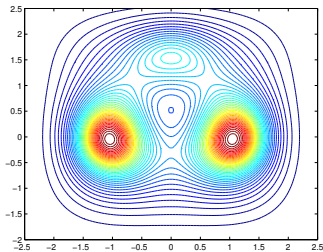
"no partial biasing" and "self-tuned stepsize"

- $\rho(t) = t^a, a \in [0, 1)$        $g(s) = s^{1-a}$

In that case, our algorithm is a discrete setting of the **Well-Tempered metadynamics** algorithm (Barducci, Bussi and Parrinello (2008))

"partial biasing" and "self-tuned stepsize" with a correlated parameter  $a$ .

# Is there a gain in such a self-tuned and partially biasing algorithm ?



Make the metastability larger by increasing  $\beta$ .

Case  $\rho(t) = t^a$  for  $a \in [0, 1)$

$g(s) = (\ln(1 + s))^{\alpha/(1-\alpha)}$  for  $\alpha \in (1/2, 1) \Rightarrow \gamma_n = O_{wp1}(1/n^\alpha)$

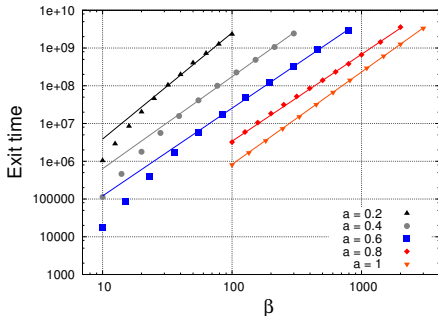
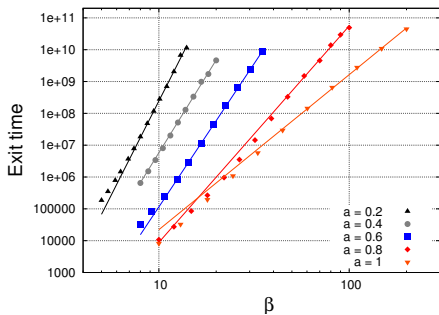


Figure: Left: Exit times for  $\alpha = 0.8$ . Right: Exit times for  $\alpha = 0.6$ .

Start from the left mode, measure the **exit time**  $T$  i.e. time to reach  $X_{n,1} > 1$

- $T \uparrow$  when  $\beta \uparrow$
- for fixed  $\beta$  and  $a$ :  $T \downarrow$  when  $\alpha \downarrow$ .
- for fixed  $\beta$  and  $\alpha$ :  $T \downarrow$  when  $a \uparrow$ .
- Linear fit with a slope indep of  $a$ :  $\ln T = c + (1 - \alpha)^{-1} \ln \beta$

# Comparison to the Well-Tempered Metadynamics

$g(s) = s^{1-a}$  ( $\Rightarrow \gamma_n = O(1/n)$ ) and  $\rho(t) = t^a$  for  $a \in (0, 1)$

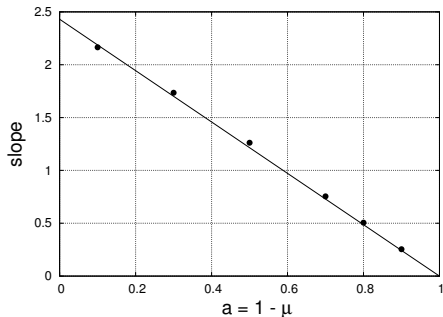
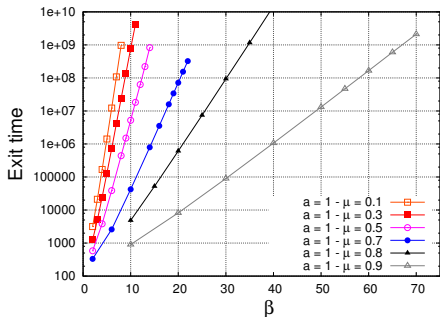


Figure: Left: Exit times for various values of  $a$ . Right: Associated slopes, fitted by  $2.43(1 - a)$ .

Exit time  $T$

- Linear fit:  $\ln T = c + 2.43(1 - a)\beta$
- For fixed  $\beta$ :  $T \downarrow$  when  $a \uparrow$



# Normalized Effective Sample Size (EF)

Case  $\gamma_n = O(1/n^\alpha)$  for  $\alpha \in (1/2, 1)$ ,  $\rho(t) = t^a$  for  $a \in [0, 1]$

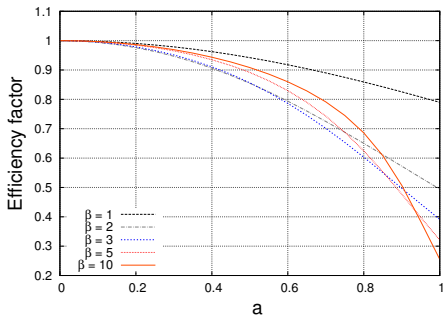


Figure: Efficiency factors  $EF(a)$  for various values of  $\beta$ .

$$EF = \frac{\left(n^{-1} \sum_{k=1}^n w(X_k)\right)^2}{\left(n^{-1} \sum_{k=1}^n w^2(X_k)\right)} \in [0, 1]$$

- By definition, when uniform weights,  $EF = 1$ .
- For fixed  $\beta$ ,  $EF \uparrow$  when  $a \downarrow$

## A new algorithm

- which estimates the free energy of  $\pi$  by a Stochastic Approximation algorithm, where the stepsize sequence  $\{\gamma_n, n \geq 0\}$  is tuned on the fly
- which provides an approximation of  $\pi$  by a set of weighted points with a controlled discrepancy of the weights.
- which requires two design parameters  $(\alpha, a)$  to be fixed by the user
  - $a$  close to 1 in the transient phase, and  $a$  close to 0 at convergence.
  - $\alpha$  close to 1/2 in the transient phase.
- far more efficient in the transient phase than Well-Tempered Metadynamics or SHUS or WL.